

# Advanced Machine Learning Summer 2019

## Part 15 – Latent Variable Models II 06.06.2019

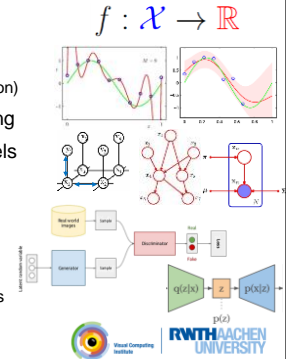
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<http://www.vision.rwth-aachen.de>



### Course Outline

- Regression Techniques
  - Linear Regression
  - Regularization (Ridge, Lasso)
  - Kernels (Kernel Ridge Regression)
- Deep Reinforcement Learning
- Probabilistic Graphical Models
  - Bayesian Networks
  - Markov Random Fields
  - Inference (exact & approximate)
  - Latent Variable Models
- Deep Generative Models
  - Generative Adversarial Networks
  - Variational Autoencoders



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### Topics of This Lecture

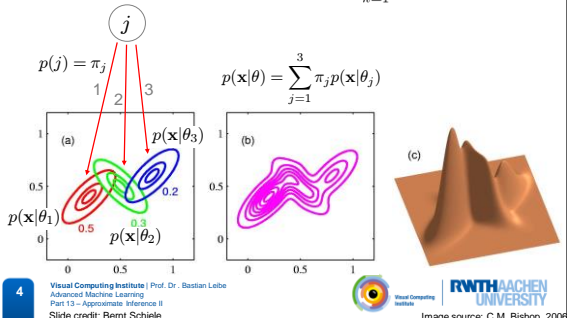
- Recap: Mixtures of Gaussians and General EM
  - Mixtures of Gaussians
  - General EM
- Mixtures of Gaussians revisited
  - General EM derivation
- The EM algorithm in general
  - Generalized EM
  - Relation to Variational inference

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### Recap: Mixtures of Gaussians

- “Generative model”  $p(\mathbf{x}) = \sum_{k=1}^K \pi_k \mathcal{N}(\mathbf{x}_n | \boldsymbol{\mu}_k, \boldsymbol{\Sigma}_k)$



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### Recap: GMMs as Latent Variable Models

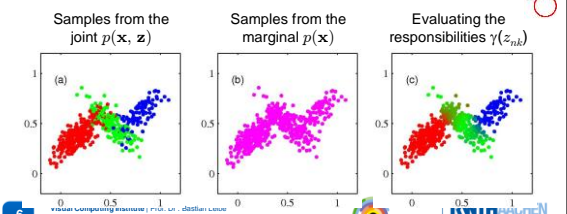
- Write GMMs in terms of latent variables  $\mathbf{z}$ 
  - Marginal distribution of  $\mathbf{x}$
$$p(\mathbf{x}) = \sum_{\mathbf{z}} p(\mathbf{x}, \mathbf{z}) = \sum_{\mathbf{z}} p(\mathbf{z})p(\mathbf{x}|\mathbf{z}) = \sum_{k=1}^K \pi_k \mathcal{N}(\mathbf{x} | \boldsymbol{\mu}_k, \boldsymbol{\Sigma}_k)$$
- Advantage of this formulation
  - We have represented the marginal distribution in terms of latent variables  $\mathbf{z}$ .
  - Since  $p(\mathbf{x}) = \sum_{\mathbf{z}} p(\mathbf{x}, \mathbf{z})$ , there is a corresponding latent variable  $\mathbf{z}_n$  for each data point  $\mathbf{x}_n$ .
  - We are now able to work with the joint distribution  $p(\mathbf{x}, \mathbf{z})$  instead of the marginal distribution  $p(\mathbf{x})$ .
  - ⇒ This will lead to significant simplifications...

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### Recap: Sampling from a Gaussian Mixture

- MoG Sampling
  - We can use **ancestral sampling** to generate random samples from a Gaussian mixture model.
    1. Generate a value  $\tilde{\mathbf{z}}$  from the marginal distribution  $p(\mathbf{z})$ .
    2. Generate a value  $\tilde{\mathbf{x}}$  from the conditional distribution  $p(\mathbf{x}|\tilde{\mathbf{z}})$ .



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## Recap: Gaussian Mixtures Revisited

- Applying the latent variable view of EM

- Goal is to maximize the log-likelihood using the observed data  $\mathbf{X}$

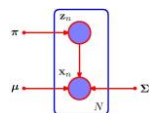
$$\log p(\mathbf{X}|\theta) = \log \left\{ \sum_{\mathbf{Z}} p(\mathbf{X}, \mathbf{Z}|\theta) \right\}$$

- Corresponding graphical model:

- Suppose we are additionally given the values of the latent variables  $\mathbf{Z}$ .

- The corresponding graphical model for the complete data now looks like this:

- ⇒ Straightforward to marginalize...



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## Recap: Alternative View of EM

- In practice, however,...

- We are not given the complete data set  $\{\mathbf{X}, \mathbf{Z}\}$ , but only the incomplete data  $\mathbf{X}$ . All we can compute about  $\mathbf{Z}$  is the posterior distribution  $p(\mathbf{Z}|\mathbf{X}, \theta)$ .

- Since we cannot use the complete-data log-likelihood, we consider instead its **expected value under the posterior distribution of the latent variables**:

$$Q(\theta, \theta^{\text{old}}) = \sum_{\mathbf{Z}} p(\mathbf{Z}|\mathbf{X}, \theta^{\text{old}}) \log p(\mathbf{X}, \mathbf{Z}|\theta)$$

- This corresponds to the **E-step** of the EM algorithm.

- In the subsequent **M-step**, we then maximize the expectation to obtain the revised parameter set  $\theta^{\text{new}}$ .

$$\theta^{\text{new}} = \arg \max_{\theta} Q(\theta, \theta^{\text{old}})$$

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## Recap: General EM Algorithm

- Algorithm

1. Choose an initial setting for the parameters  $\theta^{\text{old}}$

2. **E-step**: Evaluate  $p(\mathbf{Z}|\mathbf{X}, \theta^{\text{old}})$

3. **M-step**: Evaluate  $\theta^{\text{new}}$  given by

$$\theta^{\text{new}} = \arg \max_{\theta} Q(\theta, \theta^{\text{old}})$$

where

$$Q(\theta, \theta^{\text{old}}) = \sum_{\mathbf{Z}} p(\mathbf{Z}|\mathbf{X}, \theta^{\text{old}}) \log p(\mathbf{X}, \mathbf{Z}|\theta)$$

4. While not converged, let  $\theta^{\text{old}} \leftarrow \theta^{\text{new}}$  and return to step 2.

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## Recap: MAP-EM

- Modification for MAP

- The EM algorithm can be adapted to find MAP solutions for models for which a prior  $p(\theta)$  is defined over the parameters.
  - Only changes needed:

2. **E-step**: Evaluate  $p(\mathbf{Z}|\mathbf{X}, \theta^{\text{old}})$

3. **M-step**: Evaluate  $\theta^{\text{new}}$  given by

$$\theta^{\text{new}} = \arg \max_{\theta} Q(\theta, \theta^{\text{old}}) + \log p(\theta)$$

- ⇒ Suitable choices for the prior will remove the ML singularities!

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## Recap: Monte Carlo EM

- EM procedure

- M-step**: Maximize expectation of complete-data log-likelihood

$$Q(\theta, \theta^{\text{old}}) = \int p(\mathbf{Z}|\mathbf{X}, \theta^{\text{old}}) \log p(\mathbf{X}, \mathbf{Z}|\theta) d\mathbf{Z}$$

- For more complex models, we may not be able to compute this analytically anymore...

- Idea

- Use sampling to approximate this integral by a finite sum over samples  $\{\mathbf{Z}^{(l)}\}$  drawn from the current estimate of the posterior

$$Q(\theta, \theta^{\text{old}}) \sim \frac{1}{L} \sum_{l=1}^L \log p(\mathbf{X}, \mathbf{Z}^{(l)}|\theta)$$

- This procedure is called the **Monte Carlo EM algorithm**.

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## Gaussian Mixtures Revisited

- Applying the latent variable view of EM

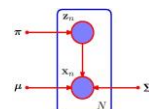
- Goal is to maximize the log-likelihood using the observed data  $\mathbf{X}$

$$\log p(\mathbf{X}|\theta) = \log \left\{ \sum_{\mathbf{Z}} p(\mathbf{X}, \mathbf{Z}|\theta) \right\}$$

- Corresponding graphical model:

- Suppose we are additionally given the values of the latent variables  $\mathbf{Z}$ .

- The corresponding graphical model for the complete data now looks like this:



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## Topics of This Lecture

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## Gaussian Mixtures Revisited

- Maximize the likelihood
  - For the complete-data set  $\{\mathbf{X}, \mathbf{Z}\}$ , the likelihood has the form

$$p(\mathbf{X}, \mathbf{Z} | \boldsymbol{\mu}, \boldsymbol{\Sigma}, \boldsymbol{\pi}) = \prod_{n=1}^N \prod_{k=1}^K \pi_k^{z_{nk}} \mathcal{N}(\mathbf{x}_n | \boldsymbol{\mu}_k, \boldsymbol{\Sigma}_k)^{z_{nk}}$$

- Taking the logarithm, we obtain

$$\log p(\mathbf{X}, \mathbf{Z} | \boldsymbol{\mu}, \boldsymbol{\Sigma}, \boldsymbol{\pi}) = \sum_{n=1}^N \sum_{k=1}^K z_{nk} \{\log \pi_k + \log \mathcal{N}(\mathbf{x}_n | \boldsymbol{\mu}_k, \boldsymbol{\Sigma}_k)\}$$

- Compared to the incomplete-data case, the order of the sum and logarithm has been interchanged.

⇒ *Much simpler solution to the ML problem.*

- Maximization w.r.t. a mean or covariance is exactly as for a single Gaussian, except that it involves only the subset of data points that are “assigned” to that component ( $z_{nk} = 1$ ).

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## Gaussian Mixtures Revisited

- Maximization w.r.t. mixing coefficients
  - More complex, since the  $\pi_k$  are coupled by the summation constraint

$$\sum_{j=1}^K \pi_j = 1$$

- Solve with a Lagrange multiplier

$$\log p(\mathbf{X}, \mathbf{Z} | \boldsymbol{\mu}, \boldsymbol{\Sigma}, \boldsymbol{\pi}) + \lambda \left( \sum_{k=1}^K \pi_k - 1 \right)$$

- Solution (after a longer derivation):

$$\pi_k = \frac{1}{N} \sum_{n=1}^N z_{nk}$$

⇒ The complete-data log-likelihood can be maximized trivially in closed form.

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## Gaussian Mixtures Revisited

- In practice, we don't have values for the latent variables
  - Consider the expectation w.r.t. the posterior distribution of the latent variables instead.
  - The posterior distribution takes the form

$$p(\mathbf{Z} | \mathbf{X}, \boldsymbol{\mu}, \boldsymbol{\Sigma}, \boldsymbol{\pi}) \propto \prod_{n=1}^N \prod_{k=1}^K [\pi_k \mathcal{N}(\mathbf{x}_n | \boldsymbol{\mu}_k, \boldsymbol{\Sigma}_k)]^{z_{nk}}$$

and factorizes over  $n$ , so that the  $\{z_n\}$  are independent under the posterior.

- Expected value of indicator variable  $z_{nk}$  under the posterior.

$$\begin{aligned} \mathbb{E}[z_{nk}] &= \frac{\sum_{z_{nk}} z_{nk} [\pi_k \mathcal{N}(\mathbf{x}_n | \boldsymbol{\mu}_k, \boldsymbol{\Sigma}_k)]^{z_{nk}}}{\sum_{z_{nj}} [\pi_j \mathcal{N}(\mathbf{x}_n | \boldsymbol{\mu}_j, \boldsymbol{\Sigma}_j)]^{z_{nj}}} \\ &= \frac{\pi_k \mathcal{N}(\mathbf{x}_n | \boldsymbol{\mu}_k, \boldsymbol{\Sigma}_k)}{\sum_{j=1}^K \pi_j \mathcal{N}(\mathbf{x}_n | \boldsymbol{\mu}_j, \boldsymbol{\Sigma}_j)} = \gamma(z_{nk}) \end{aligned}$$

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## Gaussian Mixtures Revisited

- Continuing the estimation
  - The expected value of the complete-data log-likelihood is therefore

$$\mathbb{E}_{\mathbf{Z}}[\log p(\mathbf{X}, \mathbf{Z} | \boldsymbol{\mu}, \boldsymbol{\Sigma}, \boldsymbol{\pi})] = \sum_{n=1}^N \sum_{k=1}^K \gamma(z_{nk}) \{\log \pi_k + \log \mathcal{N}(\mathbf{x}_n | \boldsymbol{\mu}_k, \boldsymbol{\Sigma}_k)\}$$

- Putting everything together

- Start by choosing some initial values for  $\boldsymbol{\mu}^{old}$ ,  $\boldsymbol{\Sigma}^{old}$ , and  $\boldsymbol{\pi}^{old}$ .
- Use these to evaluate the responsibilities (the **E-Step**).
- Keep the responsibilities fixed and maximize the above for  $\boldsymbol{\mu}^{new}$ ,  $\boldsymbol{\Sigma}^{new}$ , and  $\boldsymbol{\pi}^{new}$  (the **M-Step**).
- This leads to the familiar closed-form solutions for  $\boldsymbol{\mu}^{new}$ ,  $\boldsymbol{\Sigma}^{new}$ , and  $\boldsymbol{\pi}^{new}$ .

⇒ *This is precisely the EM algorithm for Gaussian mixtures as derived before. But we can now also apply it to other distributions.*

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## The EM Algorithm in General

- General formulation

- Given a probabilistic model with observed variables  $\mathbf{X}$ , hidden variables  $\mathbf{Z}$  and parameters  $\theta$ .
- Our goal is to maximize the likelihood given by

$$p(\mathbf{X}|\theta) = \sum_{\mathbf{Z}} p(\mathbf{X}, \mathbf{Z}|\theta)$$

- However, a direct optimization of  $p(\mathbf{X}|\theta)$  is often difficult. Optimization of the complete-data log-likelihood  $p(\mathbf{X}, \mathbf{Z}|\theta)$  is significantly easier.

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## The EM Algorithm in General

- Decomposition

- Introduce a distribution  $q(\mathbf{Z})$  over the latent variables. For any choice of  $q(\mathbf{Z})$ , the following decomposition holds

$$\log p(\mathbf{X}|\theta) = \mathcal{L}(q, \theta) + KL(q \parallel p)$$

- where

$$\mathcal{L}(q, \theta) = \sum_{\mathbf{Z}} q(\mathbf{Z}) \log \left\{ \frac{p(\mathbf{X}, \mathbf{Z}|\theta)}{q(\mathbf{Z})} \right\}$$

$$KL(q \parallel p) = - \sum_{\mathbf{Z}} q(\mathbf{Z}) \log \left\{ \frac{p(\mathbf{Z}|\mathbf{X}, \theta)}{q(\mathbf{Z})} \right\}$$

- (Proof on extra slide set)

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## Analysis of this Result

- Decomposition

- For any choice of  $q(\mathbf{Z})$ , the following decomposition holds

$$\log p(\mathbf{X}|\theta) = \mathcal{L}(q, \theta) + KL(q \parallel p)$$

$$\mathcal{L}(q, \theta) = \sum_{\mathbf{Z}} q(\mathbf{Z}) \log \left\{ \frac{p(\mathbf{X}, \mathbf{Z}|\theta)}{q(\mathbf{Z})} \right\}$$

$$KL(q \parallel p) = - \sum_{\mathbf{Z}} q(\mathbf{Z}) \log \left\{ \frac{p(\mathbf{Z}|\mathbf{X}, \theta)}{q(\mathbf{Z})} \right\}$$

- Notes (1)

- $\mathcal{L}(q, \theta)$  is a **functional** of the distribution  $q(\mathbf{Z})$  and a function of the parameters  $\theta$ .
- A functional is an operator that takes as input a function and outputs again a function.

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## Analysis of this Result

- Decomposition

- For any choice of  $q(\mathbf{Z})$ , the following decomposition holds

$$\log p(\mathbf{X}|\theta) = \mathcal{L}(q, \theta) + KL(q \parallel p)$$

$$\mathcal{L}(q, \theta) = \sum_{\mathbf{Z}} q(\mathbf{Z}) \log \left\{ \frac{p(\mathbf{X}, \mathbf{Z}|\theta)}{q(\mathbf{Z})} \right\}$$

$$KL(q \parallel p) = - \sum_{\mathbf{Z}} q(\mathbf{Z}) \log \left\{ \frac{p(\mathbf{Z}|\mathbf{X}, \theta)}{q(\mathbf{Z})} \right\}$$

- Notes (2)

- $KL(q \parallel p)$  is the **Kullback-Leibler divergence** between the distribution  $q(\mathbf{Z})$  and the posterior distribution  $p(\mathbf{Z}|\mathbf{X}, \theta)$ .
- The KL divergence satisfies  $KL(q \parallel p) \geq 0$  with  $= 0$  iff  $q(\mathbf{Z}) = p(\mathbf{Z}|\mathbf{X}, \theta)$ .

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## Analysis of this Result

- Decomposition

- For any choice of  $q(\mathbf{Z})$ , the following decomposition holds

$$\log p(\mathbf{X}|\theta) = \mathcal{L}(q, \theta) + KL(q \parallel p)$$

$$\mathcal{L}(q, \theta) = \sum_{\mathbf{Z}} q(\mathbf{Z}) \log \left\{ \frac{p(\mathbf{X}, \mathbf{Z}|\theta)}{q(\mathbf{Z})} \right\}$$

$$KL(q \parallel p) = - \sum_{\mathbf{Z}} q(\mathbf{Z}) \log \left\{ \frac{p(\mathbf{Z}|\mathbf{X}, \theta)}{q(\mathbf{Z})} \right\}$$

- Notes (3)

- It therefore follows that  $\mathcal{L}(q, \theta) \leq \log p(\mathbf{X}|\theta)$ .
- In other words:  $\mathcal{L}(q, \theta)$  is a **lower bound** on  $\log p(\mathbf{X}|\theta)$ .
- We can now use this result in order to analyze how EM works...

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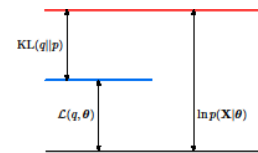
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## Analysis of EM

- Decomposition

$$\log p(\mathbf{X}|\theta) = \mathcal{L}(q, \theta) + KL(q \parallel p)$$



- Interpretation

- $\mathcal{L}(q, \theta)$  is a **lower bound** on  $\log p(\mathbf{X}|\theta)$ .
- The approximation comes from the fact that we use an approximative distribution  $q(\mathbf{Z}) = p(\mathbf{Z}|\mathbf{X}, \theta^{old})$  instead of the (unknown) real posterior.
- The KL divergence measures the difference between the approximative distribution  $q(\mathbf{Z})$  and the real posterior  $p(\mathbf{Z}|\mathbf{X}, \theta)$ .
- In every EM iteration, we try to make this difference smaller.

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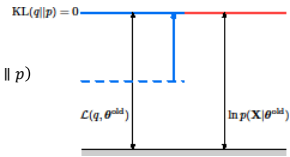
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## Analysis of EM

### • Decomposition

$$\log p(\mathbf{X}|\theta) = \mathcal{L}(q, \theta) + KL(q \parallel p)$$



### • E-Step

- Suppose the current value of the parameter vector is  $\theta^{old}$ .
- The E-step maximizes the lower bound  $\mathcal{L}(q, \theta)$  w.r.t.  $q(\mathbf{Z})$  while holding  $\theta^{old}$  fixed.
- The solution to this maximization problem of  $\log p(\mathbf{X}|\theta^{old})$  will occur when the KL divergence vanishes, i.e. when  $q(\mathbf{Z}) = p(\mathbf{Z}|\mathbf{X}, \theta^{old})$ .
- In this case, the lower bound equals the log-likelihood.

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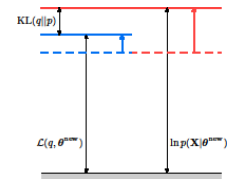


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## Analysis of EM

### • Decomposition

$$\log p(\mathbf{X}|\theta) = \mathcal{L}(q, \theta) + KL(q \parallel p)$$



### • M-Step

- In the M-step, the distribution  $q(\mathbf{Z})$  is held fixed and the lower bound  $\mathcal{L}(q, \theta)$  is maximized w.r.t.  $\theta$  to give some new value  $\theta^{new}$ .
- This causes the lower bound  $\mathcal{L}$  to increase (unless it is already at maximum), which will cause the log-likelihood to increase.
- Because  $q(\mathbf{Z})$  is determined using the old parameter values, it will not equal the posterior distribution  $p(\mathbf{Z}|\mathbf{X}, \theta^{new})$  and there will be a non-zero KL divergence.

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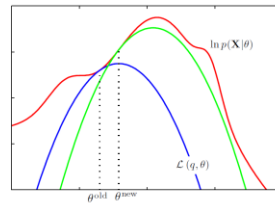
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## Analysis of EM

### • Visualization in the space of parameters



### • The EM algorithm alternately

- Computes a lower bound on the log-likelihood for the current parameters values
- And then maximizes this bound to obtain the new parameter values.

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## References and Further Reading

### • More information about EM and MoG estimation is available in Chapter 9 of Bishop's book (recommendable to read).

Christopher M. Bishop  
Pattern Recognition and Machine Learning  
Springer, 2006



### • Additional information

- A.P. Dempster, N.M. Laird, D.B. Rubin, „Maximum-Likelihood from incomplete data via EM algorithm“, In J. Royal Statistical Society, Series B. Vol 39, 1977
- J.A. Bilmes, „A Gentle Tutorial of the EM Algorithm and its Application to Parameter Estimation for Gaussian Mixture and Hidden Markov Models“, TR-97-021, ICSI, U.C. Berkeley, CA, USA

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