

Advanced Machine Learning Summer 2019

Part 17 – Generative Adversarial Networks 26.06.2019

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<http://www.vision.rwth-aachen.de>

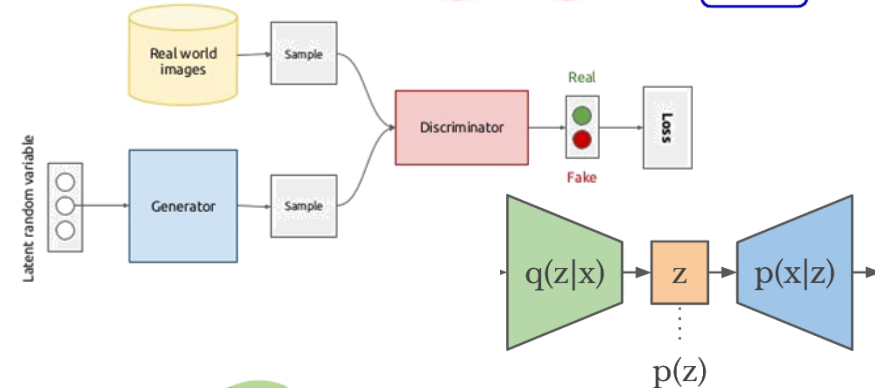
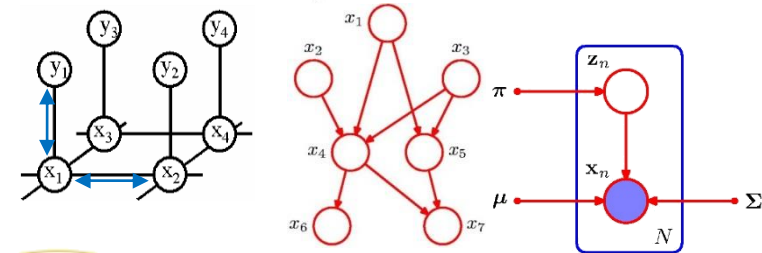
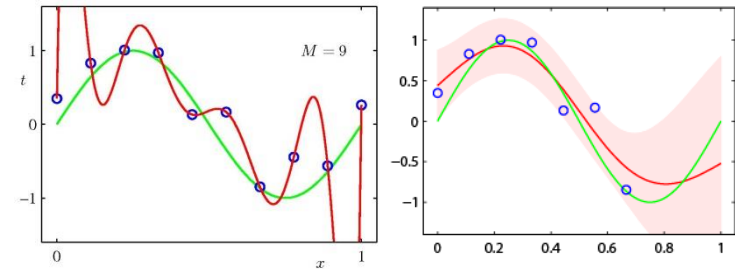


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Course Outline

- Regression Techniques
 - Linear Regression
 - Regularization (Ridge, Lasso)
 - Kernels (Kernel Ridge Regression)
- Deep Reinforcement Learning
- Probabilistic Graphical Models
 - Bayesian Networks
 - Markov Random Fields
 - Inference (exact & approximate)
 - Latent Variable Models
- Deep Generative Models
 - Generative Adversarial Networks
 - Variational Autoencoders

$$f : \mathcal{X} \rightarrow \mathbb{R}$$



Topics of This Lecture

- **Recap: Bayesian Mixture Models**
- **Generative Adversarial Networks (GANs)**
 - Generative networks
 - GAN loss and training procedure
- **Applications & Extensions**
 - GANs for image generation
 - GANs for superresolution
 - Conditional GANs
- **Problems of GANs**
 - Problems during training
 - Conceptual problems
 - Extension: Wasserstein GANs

Recap: Bayesian Mixture Models

- Let's be Bayesian about mixture models
 - Place priors over our parameters
 - Again, introduce variable \mathbf{z}_n as indicator which component data point \mathbf{x}_n belongs to.

$$\mathbf{z}_n | \boldsymbol{\pi} \sim \text{Multinomial}(\boldsymbol{\pi})$$

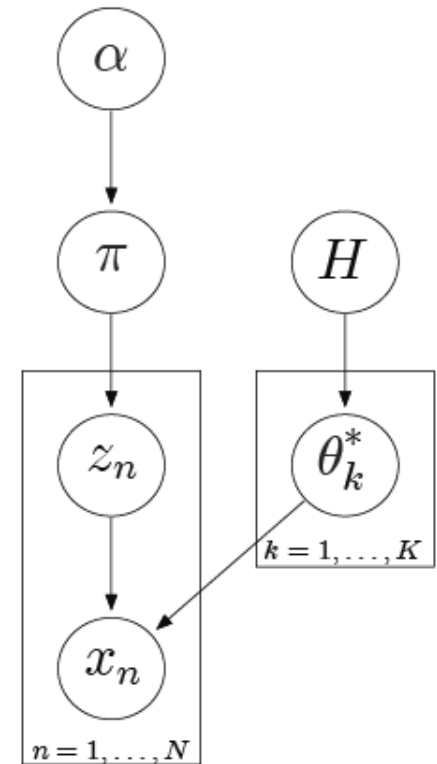
$$\mathbf{x}_n | \mathbf{z}_n = k, \boldsymbol{\mu}, \boldsymbol{\Sigma} \sim \mathcal{N}(\boldsymbol{\mu}_k, \boldsymbol{\Sigma}_k)$$

- Introduce **conjugate priors** over parameters

$$\boldsymbol{\pi} \sim \text{Dirichlet}\left(\frac{\alpha}{K}, \dots, \frac{\alpha}{K}\right)$$

$$\boldsymbol{\mu}_k, \boldsymbol{\Sigma}_k \sim H = \mathcal{N} - \mathcal{IW}(0, s, d, \phi)$$

“Normal – Inverse Wishart”



Recap: Bayesian Mixture Models

- Full Bayesian Treatment

- Given a dataset, we are interested in the cluster assignments

$$p(\mathbf{Z}|\mathbf{X}) = \frac{p(\mathbf{X}|\mathbf{Z})p(\mathbf{Z})}{\sum_{\mathbf{Z}} p(\mathbf{X}|\mathbf{Z})p(\mathbf{Z})}$$

where the likelihood is obtained by marginalizing over the parameters θ

$$\begin{aligned} p(\mathbf{X}|\mathbf{Z}) &= \int p(\mathbf{X}|\mathbf{Z}, \theta)p(\theta)d\theta \\ &= \int \prod_{n=1}^N \prod_{k=1}^K p(\mathbf{x}_n|z_{nk}, \theta_k)p(\theta_k|H)d\theta \end{aligned}$$

- The posterior over assignments is intractable!

- Denominator requires summing over all possible partitions of the data into K groups!

⇒ Need efficient approximate inference methods to solve this...

Recap: Mixture Models with Dirichlet Priors

- Integrating out the mixing proportions π

$$\begin{aligned} p(\mathbf{z}|\alpha) &= \int p(\mathbf{z}|\boldsymbol{\pi})p(\boldsymbol{\pi}|\alpha)d\boldsymbol{\pi} \\ &= \frac{\Gamma(\alpha)}{\Gamma(N + \alpha)} \prod_{k=1}^K \frac{\Gamma(N_k + \alpha/K)}{\Gamma(\alpha/K)} \end{aligned}$$

- Conditional probabilities

- Examine the conditional of \mathbf{z}_n given all other variables \mathbf{z}_{-n}

$$\begin{aligned} p(z_{nk} = 1 | \mathbf{z}_{-n}, \alpha) &= \frac{p(z_{nk} = 1, \mathbf{z}_{-n} | \alpha)}{p(\mathbf{z}_{-n} | \alpha)} \\ &= \frac{N_{-n,k} + \alpha/K}{N - 1 + \alpha} \end{aligned} \quad N_{-n,k} \stackrel{\text{def}}{=} \sum_{i=1, i \neq n}^N z_{ik}$$

⇒ The **more populous** a class is, the more likely it is to be joined!

Recap: Infinite Dirichlet Mixture Models

- Conditional probabilities: Finite K

$$p(z_{nk} = 1 | \mathbf{z}_{-n}, \alpha) = \frac{N_{-n,k} + \alpha/K}{N - 1 + \alpha}, \quad N_{-n,k} \stackrel{\text{def}}{=} \sum_{i=1, i \neq n}^N z_{ik}$$

- Conditional probabilities: Infinite K

– Taking the limit as $K \rightarrow \infty$ yields the conditionals

$$p(z_{nk} = 1 | \mathbf{z}_{-n}, \alpha) = \begin{cases} \frac{N_{-n,k}}{N-1+\alpha} & \text{if } k \text{ represented} \\ \frac{\alpha}{N-1+\alpha} & \text{if all } k \text{ not represented} \end{cases}$$

– **Left-over mass** $\alpha \Rightarrow$ countably infinite number of indicator settings

Recap: Gibbs Sampling for Finite Mixtures

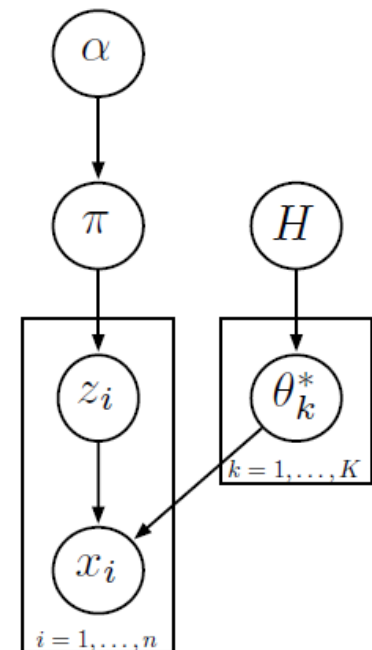
- We need approximate inference here
 - **Gibbs Sampling**: Conditionals are simple to compute

$$p(\mathbf{z}_n = k | \text{others}) \propto \sum_{k=1}^K \pi_k \mathcal{N}(\mathbf{x}_n | \boldsymbol{\mu}_k, \boldsymbol{\Sigma}_k)$$

$$\boldsymbol{\pi} | \mathbf{z} \sim \text{Dir}(N_1 + \alpha/K, \dots, N_K + \alpha/K)$$

$$\boldsymbol{\mu}_k, \boldsymbol{\Sigma}_k | \text{others} \sim \mathcal{N} - \mathcal{IW}(v', s', d', \phi')$$

- However, this will be rather inefficient...
 - In each iteration, algorithm can only change the assignment for individual data points.
 - There are often groups of data points that are associated with high probability to the same component. \Rightarrow Unlikely that group is moved.
 - Better performance by **collapsed Gibbs sampling** which integrates out the parameters $\boldsymbol{\pi}$, $\boldsymbol{\mu}$, $\boldsymbol{\Sigma}$.



Recap: Collapsed Finite Bayesian Mixture

- More efficient algorithm
 - Conjugate priors allow analytic integration of some parameters
 - Resulting sampler operates on reduced space of cluster assignments (implicitly considers all possible cluster shapes)

- Procedure

- The model implies the factorization

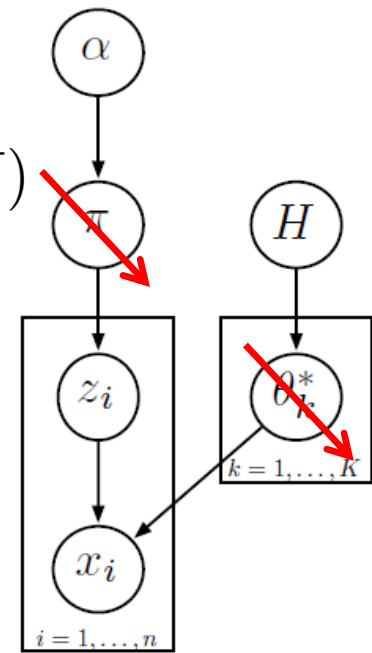
$$p(\mathbf{z}_n | \mathbf{z}_{-n}, \mathbf{x}, \alpha, H) \propto p(\mathbf{z}_n | \mathbf{z}_{-n}, \alpha) p(\mathbf{x}_n | \mathbf{z}, \mathbf{x}_{-n}, H)$$

- Derive

$$p(\mathbf{z} | \alpha) = \int p(\mathbf{z} | \boldsymbol{\pi}) p(\boldsymbol{\pi} | \alpha) d\boldsymbol{\pi} \quad \checkmark$$

$$p(\mathbf{x}_n | \mathbf{z}_n, H) = \int \sum_{k=1}^K z_{nk} p(\mathbf{x}_n | \boldsymbol{\theta}_k) p(\boldsymbol{\theta}_k | H) d\boldsymbol{\theta} \quad \checkmark$$

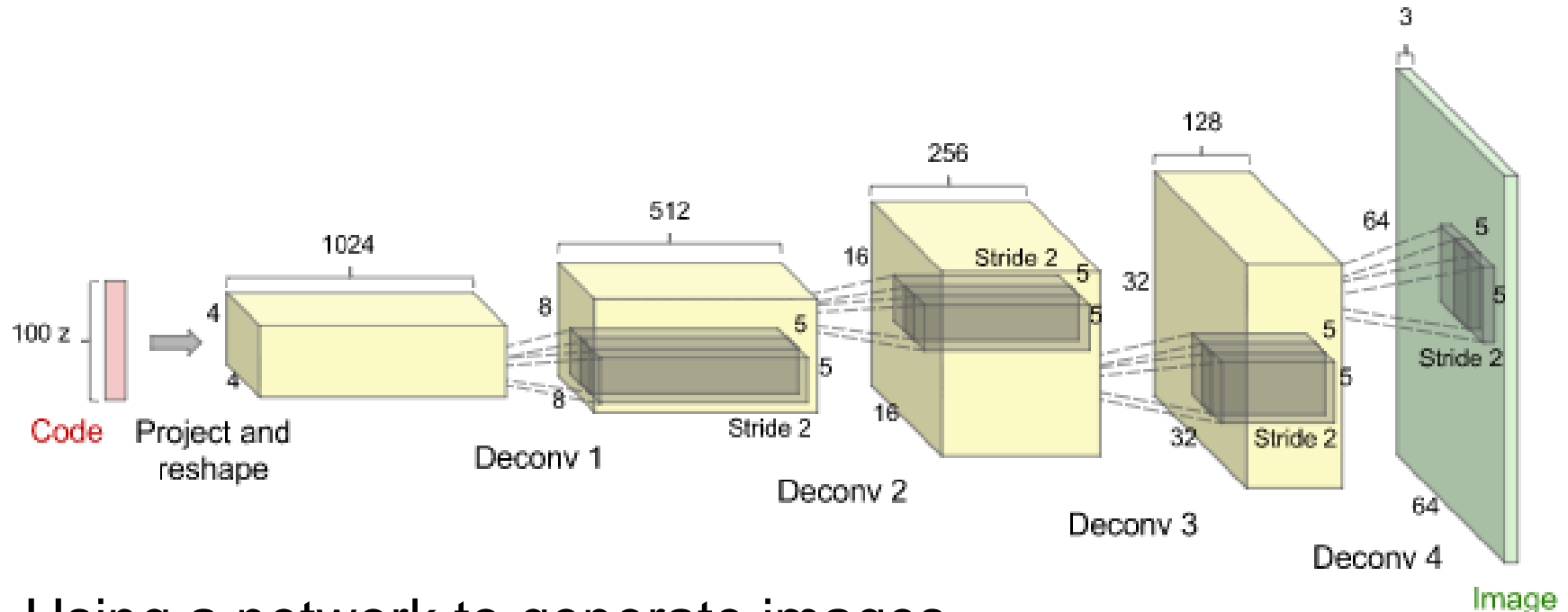
⇒ Conjugate prior, Normal - Inverse Wishart



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- **Generative Adversarial Networks (GANs)**
 - Generative networks
 - GAN loss and training procedure
- Applications & Extensions
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 - GANs for superresolution
 - Conditional GANs
- Problems of GANs
 - Problems during training
 - Conceptual problems
 - Extension: Wasserstein GANs

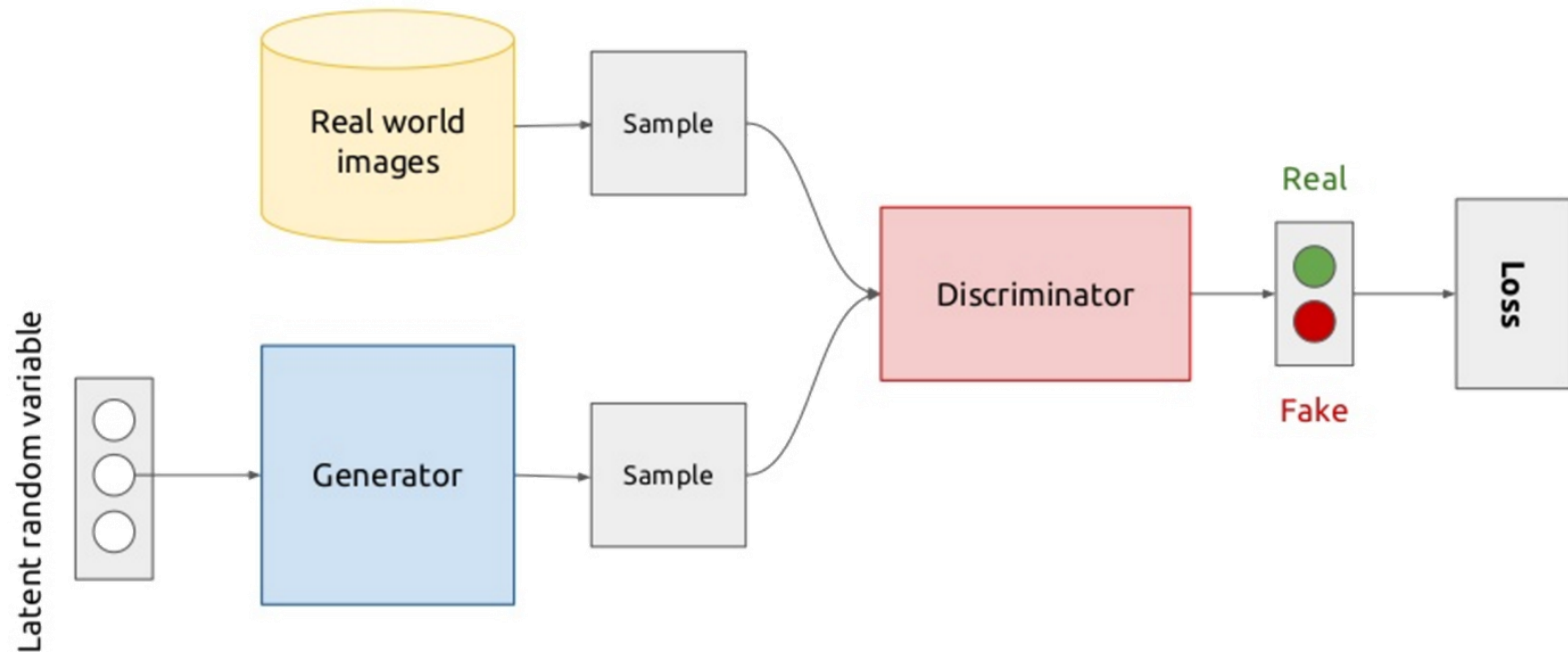
Generative Networks



- Using a network to generate images
 - Sampling from noise distribution
 - Sequence of upsampling layers to generate an output image
 - *How can we train such a model to produce the desired output?*

Generative Adversarial Networks (GANs)

- Conceptual view



- Main idea

- Simultaneously train an image **generator G** and a **discriminator D** .
- Interpreted as a two-player game

Two-Player Game

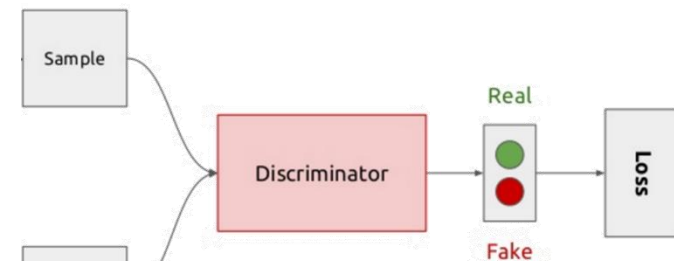
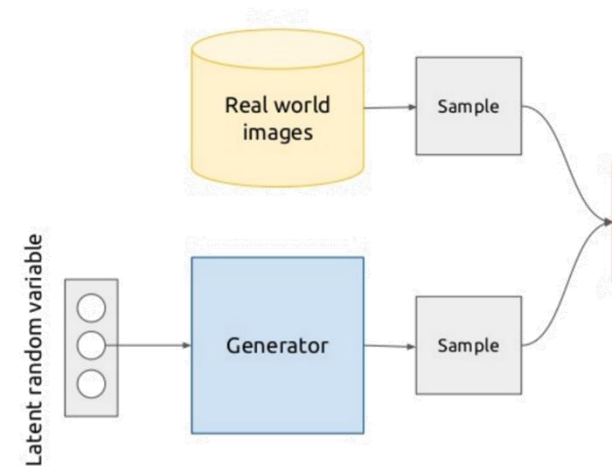
- **Generator**

- Tries to draw samples from $p(\mathbf{x})$.
- Analogy: *counterfeiter*



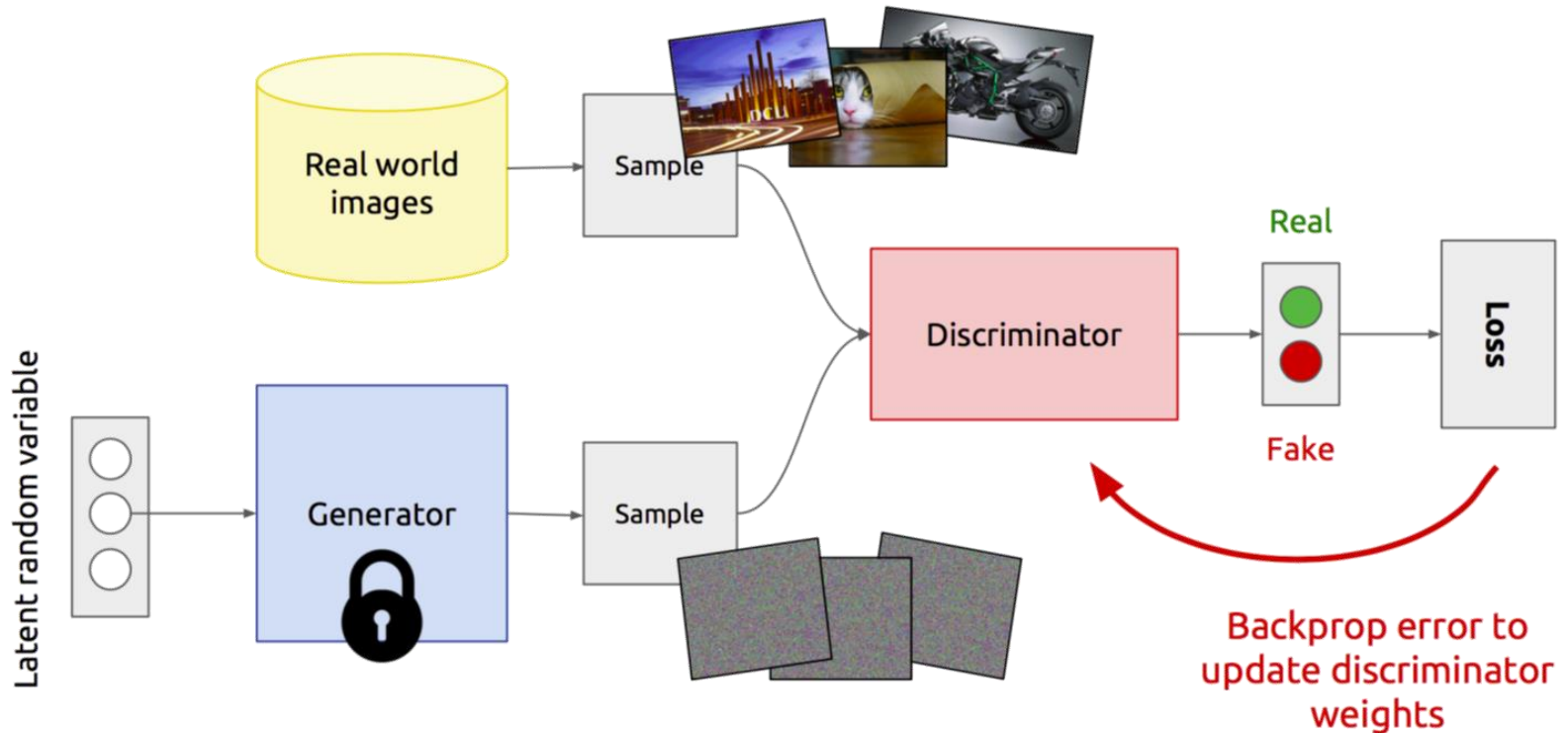
- **Discriminator**

- Tries to determine whether the sample came from the generator or the data distribution.
- Analogy: *police investigator*



- Both generator and discriminator are deep networks
 - We can train them with backprop.

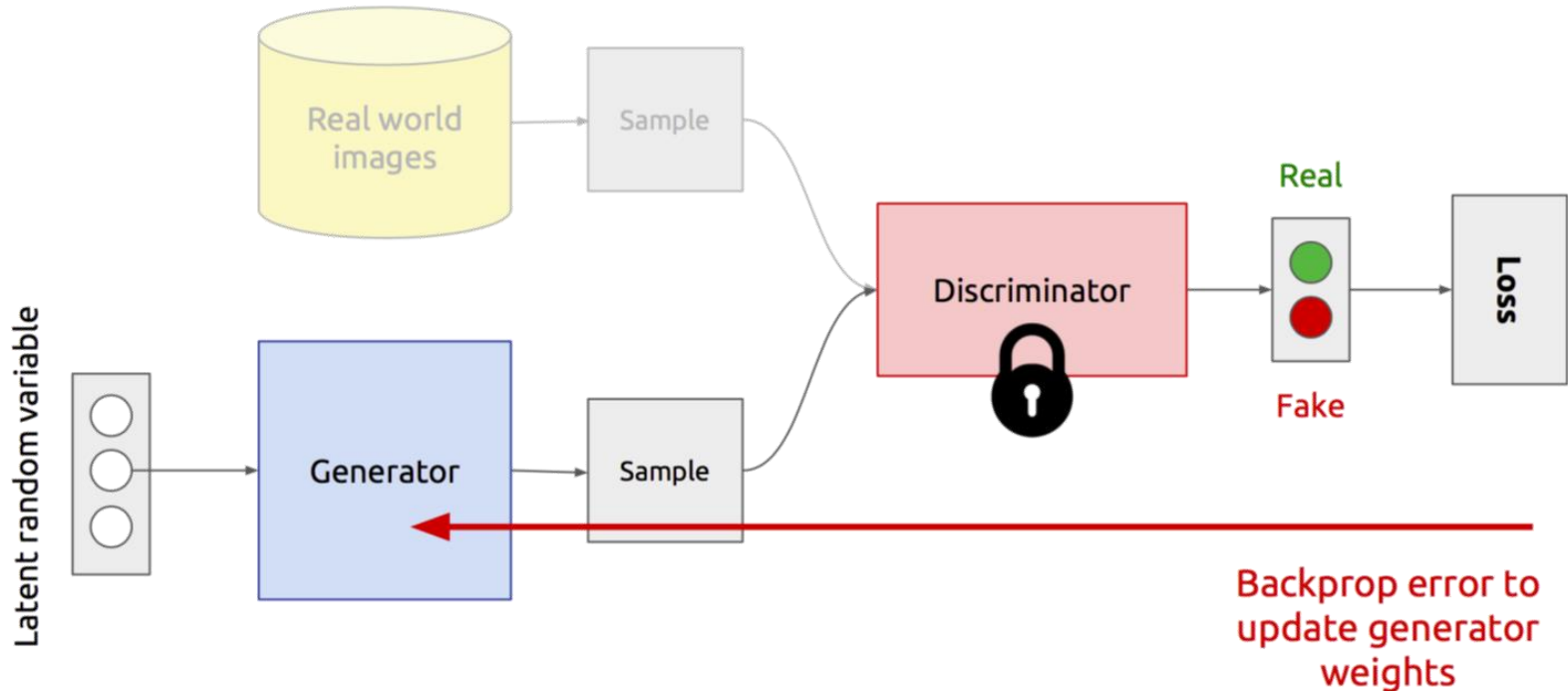
Training the Discriminator



- Procedure

- Fix generator weights
- Train discriminator to distinguish between real and generated images

Training the Generator



- Procedure

- Fix discriminator weights
- Sample from generator
- Backprop through discriminator to update generator weights

Formalizing This Procedure

- This corresponds to a two-player minimax game:

$$\min_G \max_D V(D, G) = \mathbb{E}_{\mathbf{x} \sim p_{data}(\mathbf{x})} [\log D(\mathbf{x})] + \mathbb{E}_{\mathbf{z} \sim p_{\mathbf{z}}(\mathbf{z})} [\log (1 - D(G(\mathbf{z})))]$$

- Explanation

- Train D to maximize the probability of assigning the correct label to both **training examples** and **samples from G** .
- Simultaneously train G to minimize $\log(1 - D(G(\mathbf{z})))$.

- The Nash equilibrium of this game is achieved at

- $p_g(\mathbf{x}) = p_{data}(\mathbf{x}) \quad \forall \mathbf{x}$
- $D(\mathbf{x}) = \frac{1}{2} \quad \forall \mathbf{x}$

GAN Algorithm

Algorithm 1 Minibatch stochastic gradient descent training of generative adversarial nets. The number of steps to apply to the discriminator, k , is a hyperparameter. We used $k = 1$, the least expensive option, in our experiments.

for number of training iterations **do**

for k steps **do**

- Sample minibatch of m noise samples $\{z^{(1)}, \dots, z^{(m)}\}$ from noise prior $p_g(z)$.
- Sample minibatch of m examples $\{x^{(1)}, \dots, x^{(m)}\}$ from data generating distribution $p_{\text{data}}(x)$.
- Update the discriminator by ascending its stochastic gradient:

$$\nabla_{\theta_d} \frac{1}{m} \sum_{i=1}^m \left[\log D(x^{(i)}) + \log \left(1 - D(G(z^{(i)})) \right) \right].$$

Discriminator updates

end for

- Sample minibatch of m noise samples $\{z^{(1)}, \dots, z^{(m)}\}$ from noise prior $p_g(z)$.
- Update the generator by descending its stochastic gradient:

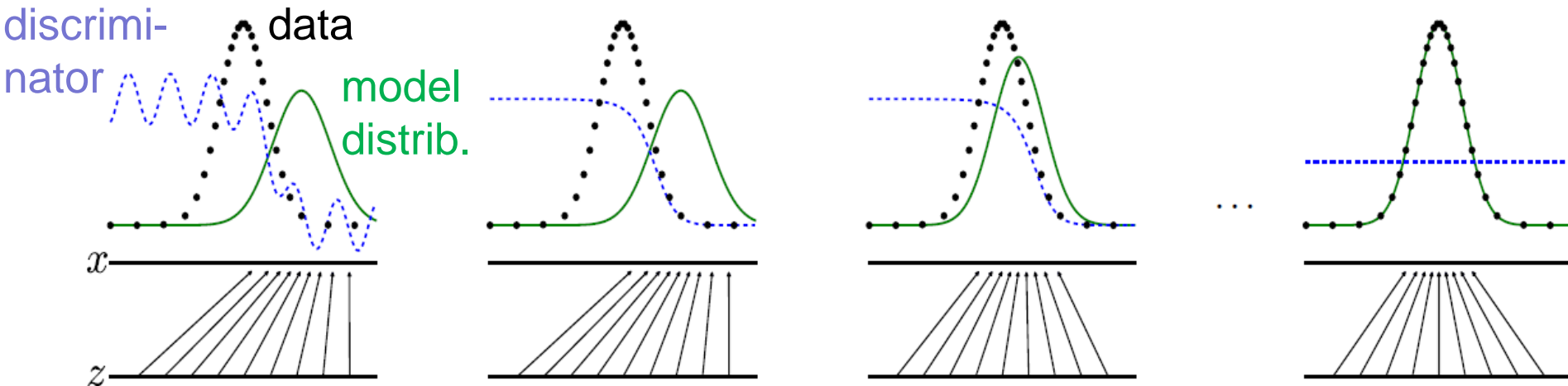
$$\nabla_{\theta_g} \frac{1}{m} \sum_{i=1}^m \log \left(1 - D(G(z^{(i)})) \right).$$

Generator updates

end for

The gradient-based updates can use any standard gradient-based learning rule. We used momentum in our experiments.

Intuition



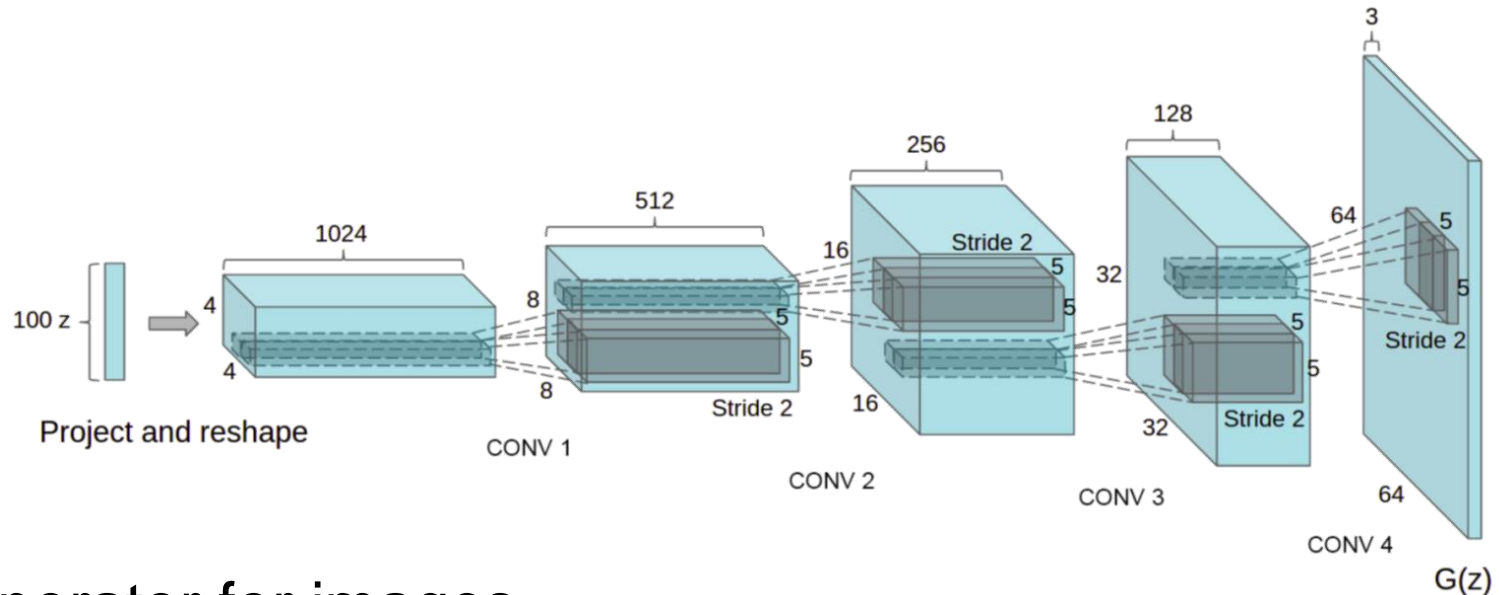
- Behavior near convergence

- In the inner loop, D is trained to discriminate samples from data.
- Gradient of D guides G to flow to regions that are more likely to be classified as data.
- After several steps of training, G and D will reach a point at which they cannot further improve, because $p_g = p_{data}$.
- Now, the discriminator is unable to differentiate between the two distributions, i.e., $D(x) = 0.5$.

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Example: Deep Convolutional GAN (DCGAN)



- Generator for images
 - Remove fully-connected layers
 - Upsampling with **fractional strided convolutions**
 - **Batch normalization** after each layer (important!)
 - Use **ReLU** in generator for hidden layers, tanh for output layer
 - Use **Leaky ReLU** in the discriminator for all layers

Example Application: Image Generation



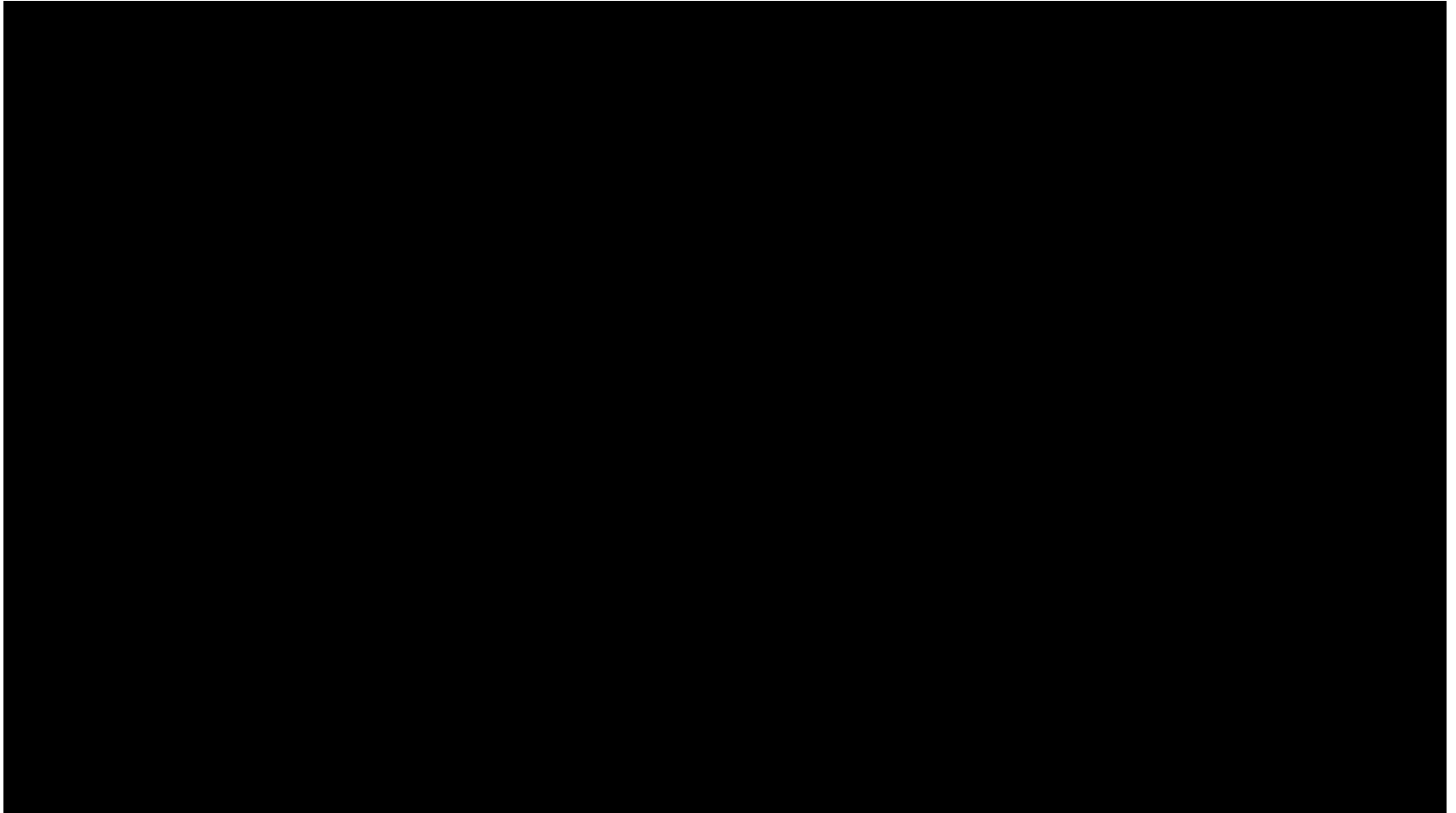
- Generating bedroom images
 - Each sample is generated from a sampled random number

Example Application: Image Generation



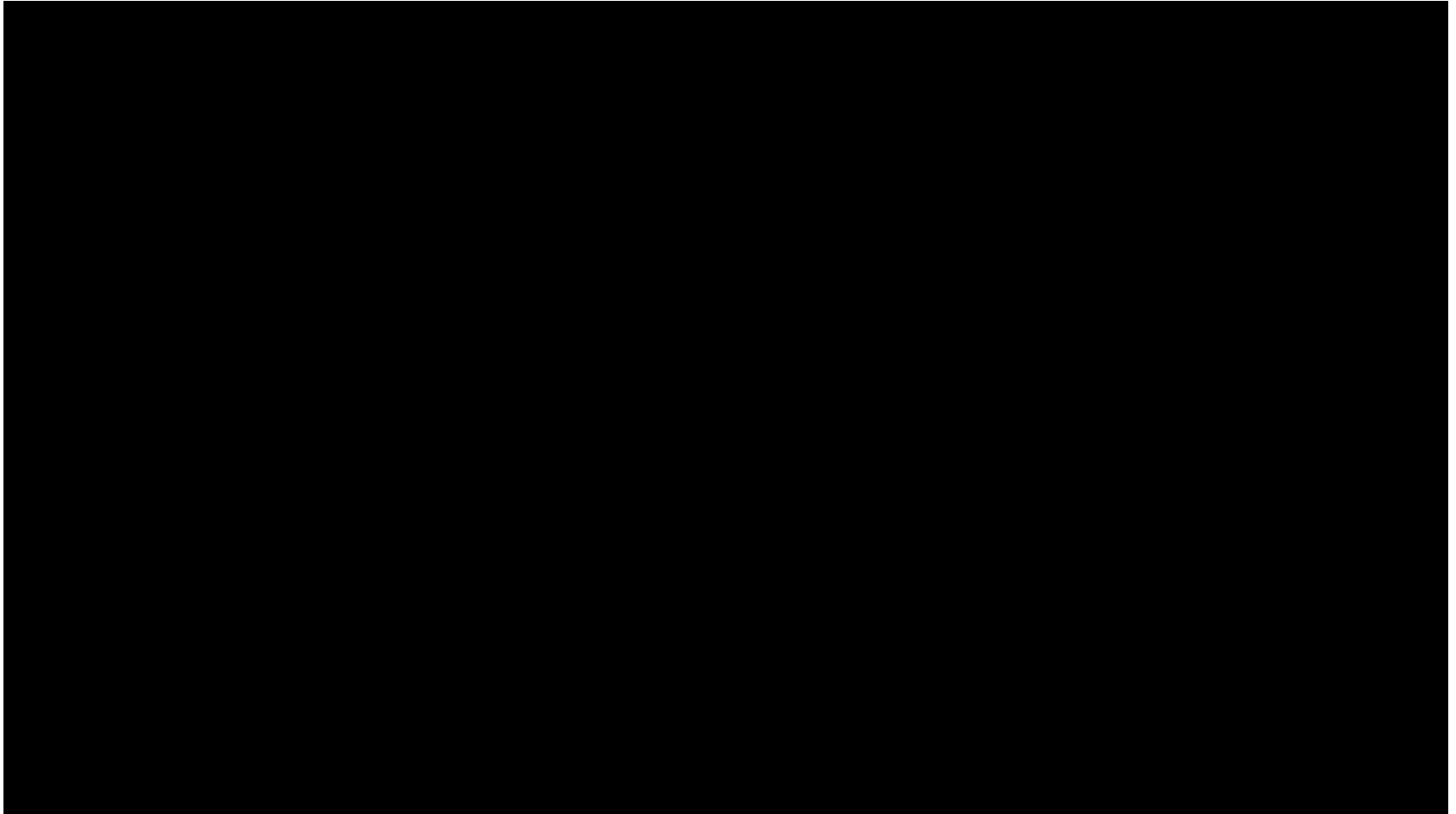
- Interpolating between the random points in latent space...

Interpolation between Face Images



Karras et al, “*Progressive growing of GANs for improved quality, stability, and variation*”, ICLR’18

Interpolation between Arbitrary Images



Karras et al, “*Progressive growing of GANs for improved quality, stability, and variation*”, ICLR’18

Example Application: Super-Resolution (SRGAN)

bicubic



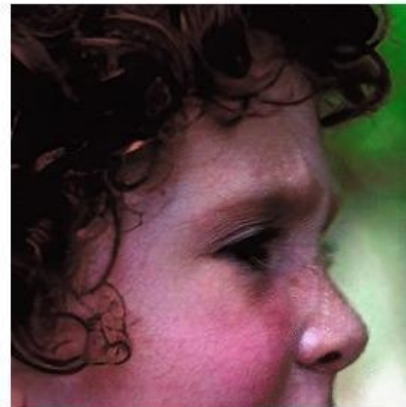
SRResNet



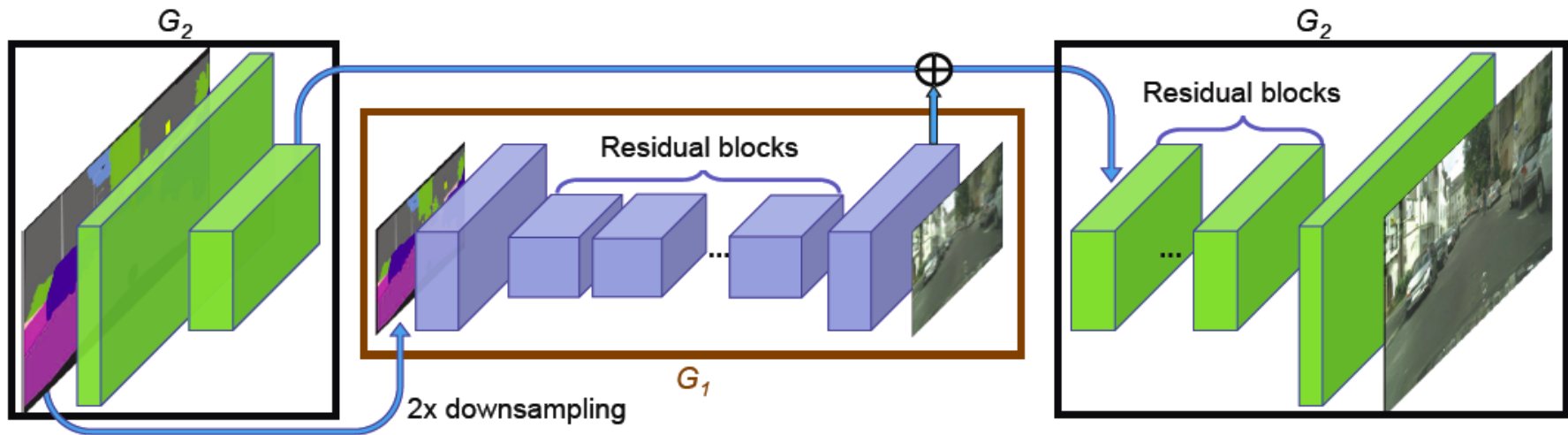
SRGAN



original



Extension: Conditional GANs



- Idea

- Condition the latent space representation on an input image
- Used to create the pix2pix network

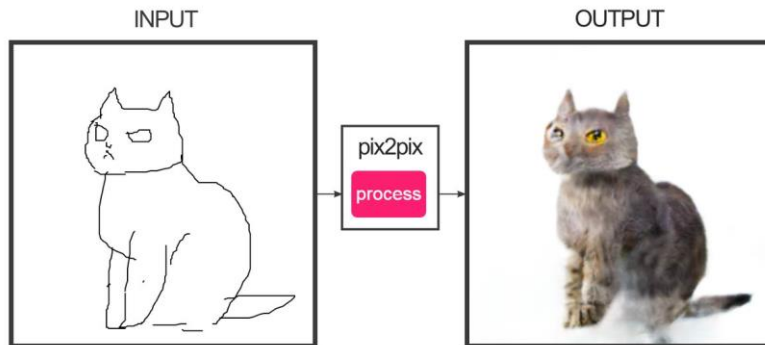
P. Isola, J.-Y. Zhu, T. Zhou, and A. A. Efros. Image-to-image translation with conditional adversarial networks. CVPR 2017.

Extension: Conditional GANs

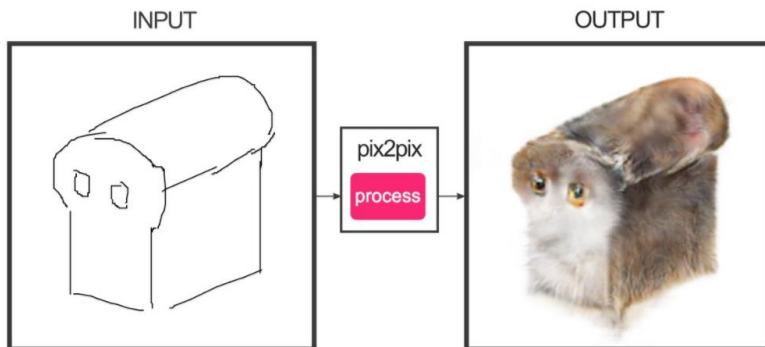


T-C. Wang, M-Y. Liu, J-Y. Zhu, A. Tao, J. Kautz, B. Catanzaro, High-Resolution Image Synthesis and Semantic Manipulation with Conditional GANs, CVPR 2018.

Artist Project: edges2cats [Christopher Hesse]



Vitaly Vidmirov @vvid



Ivy Tasi @ivymyt



@ka92

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What Can Possibly Go Wrong? Problems with GANs

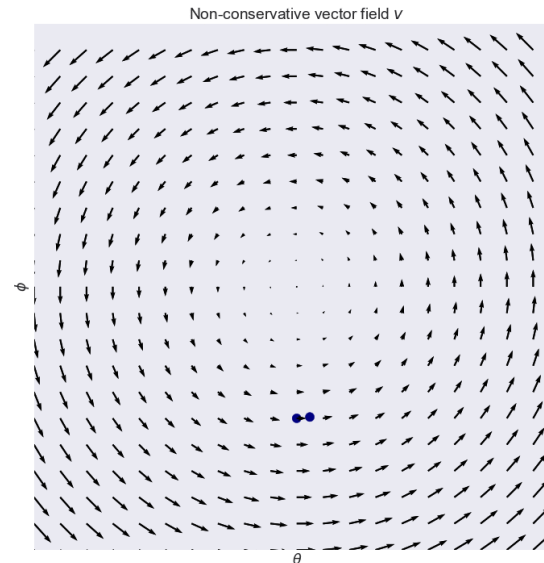
- Problem 1: Vanishing gradients
 - When the discriminator is perfect, the loss function falls to zero.
 - No gradient to update the loss during learning iterations.
 - Dilemma: **Walking a fine line...**
 - Discriminator behaves badly \Rightarrow generator does not have accurate feedback
 - Discriminator does a great job \Rightarrow gradient of the loss drops close to zero

What Can Possibly Go Wrong? Problems with GANs



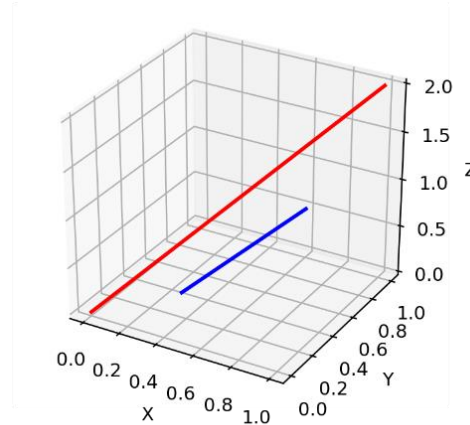
- Problem 2: Mode collapse
 - Even though the generator might be able to trick the discriminator, it may fail to represent the complex real-world data distribution.
 - Training gets stuck in a small space with little variety

What Can Possibly Go Wrong? Problems with GANs



- Problem 3: Non-convergence
 - GANs involve two players
 - Each model updates its cost independently
 - This means we are performing **simultaneous gradient descent**
 - Problem: might not converge to Nash equilibrium

What Can Possibly Go Wrong? Problems with GANs



- Problem 4: Low-dimensional support
 - Both p_{data} and p_g lie on low-dimensional manifolds.
 - Those manifolds most likely do not intersect
 - The Jensen divergence implicitly optimized in GANs cannot deal with this well.
 - **Wasserstein GANs** fix this by introducing a different loss function.

Summary

- Advantages
 - GANs can be trained with backpropagation
 - Generated images are sharper than from VAEs
 - Robust to overfitting, since generator never sees the training data
 - Fast process: single forward pass generates a single sample
- Disadvantages
 - GANs are well known for being delicate and unstable
 - Problems with non-convergence
 - Problems with mode collapse
- Extensions
 - **Wasserstein GANs** fix several major problems in the GAN formulation
 - **Energy-based GANs** allow general loss functions

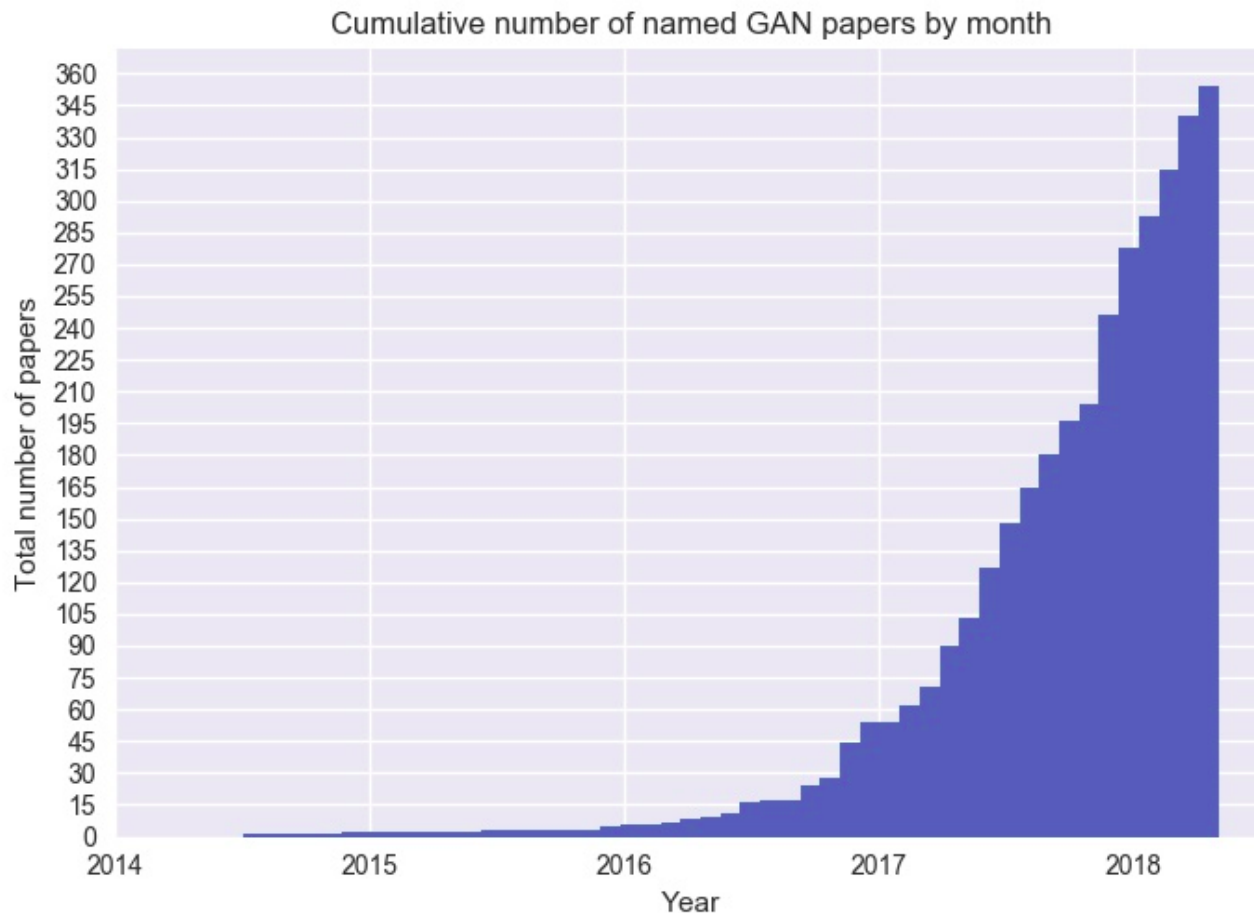
2017: Explosion of GANs

• “The GAN Zoo”

- GAN - Generative Adversarial Networks
- 3D-GAN - Learning a Probabilistic Latent Space of Object Shapes via 3D Generative-Adversarial Modeling
- acGAN - Face Aging With Conditional Generative Adversarial Networks
- AC-GAN - Conditional Image Synthesis With Auxiliary Classifier GANs
- AdaGAN - AdaGAN: Boosting Generative Models
- AEGAN - Learning Inverse Mapping by Autoencoder based Generative Adversarial Nets
- AffGAN - Amortised MAP Inference for Image Super-resolution
- AL-CGAN - Learning to Generate Images of Outdoor Scenes from Attributes and Semantic Layouts
- ALI - Adversarially Learned Inference
- AM-GAN - Generative Adversarial Nets with Labeled Data by Activation Maximization
- AnoGAN - Unsupervised Anomaly Detection with Generative Adversarial Networks to Guide Marker Discovery
- ArtGAN - ArtGAN: Artwork Synthesis with Conditional Categorical GANs
- b-GAN - b-GAN: Unified Framework of Generative Adversarial Networks
- Bayesian GAN - Deep and Hierarchical Implicit Models
- BEGAN - BEGAN: Boundary Equilibrium Generative Adversarial Networks
- BiGAN - Adversarial Feature Learning
- BS-GAN - Boundary-Seeking Generative Adversarial Networks
- CGAN - Conditional Generative Adversarial Nets
- CaloGAN - CaloGAN: Simulating 3D High Energy Particle Showers in Multi-Layer Electromagnetic Calorimeters with Generative Adversarial Networks
- CCGAN - Semi-Supervised Learning with Context-Conditional Generative Adversarial Networks
- CatGAN - Unsupervised and Semi-supervised Learning with Categorical Generative Adversarial Networks
- CoGAN - Coupled Generative Adversarial Networks
- Context-RNN-GAN - Contextual RNN-GANs for Abstract Reasoning Diagram Generation
- C-RNN-GAN - C-RNN-GAN: Continuous recurrent neural networks with adversarial training
- CS-GAN - Improving Neural Machine Translation with Conditional Sequence Generative Adversarial Nets
- CVAE-GAN - CVAE-GAN: Fine-Grained Image Generation through Asymmetric Training
- CycleGAN - Unpaired Image-to-Image Translation using Cycle-Consistent Adversarial Networks
- DTN - Unsupervised Cross-Domain Image Generation
- DCGAN - Unsupervised Representation Learning with Deep Convolutional Generative Adversarial Networks
- DiscoGAN - Learning to Discover Cross-Domain Relations with Generative Adversarial Networks
- DR-GAN - Disentangled Representation Learning GAN for Pose-Invariant Face Recognition
- DualGAN - DualGAN: Unsupervised Dual Learning for Image-to-Image Translation
- EBGAN - Energy-based Generative Adversarial Network
- f-GAN - f-GAN: Training Generative Neural Samplers using Variational Divergence Minimization
- FF-GAN - Towards Large-Pose Face Frontalization in the Wild
- GAWWN - Learning What and Where to Draw
- GeneGAN - GeneGAN: Learning Object Transfiguration and Attribute Subspace from Unpaired Data
- Geometric GAN - Geometric GAN
- GoGAN - Gang of GANs: Generative Adversarial Networks with Maximum Margin Ranking
- GP-GAN - GP-GAN: Towards Realistic High-Resolution Image Blending
- IAN - Neural Photo Editing with Introspective Adversarial Networks
- iGAN - Generative Visual Manipulation on the Natural Image Manifold
- IcGAN - Invertible Conditional GANs for image editing
- ID-CGAN - Image De-raining Using a Conditional Generative Adversarial Network
- Improved GAN - Improved Techniques for Training GANs
- InfoGAN - InfoGAN: Interpretable Representation Learning by Information Maximizing Generative Adversarial Nets
- LAGAN - Learning Particle Physics by Example: Location-Aware Generative Adversarial Networks for Physics Synthesis
- LAPGAN - Deep Generative Image Models using a Laplacian Pyramid of Adversarial Networks

<https://github.com/hindupuravinash/the-gan-zoo>

Interest in GANs Is Still Growing...



<https://github.com/hindupuravinash/the-gan-zoo>

References

- Original GAN
 - I.J. Goodfellow, J. Pouget-Abadie, M. Mirza, B. Xu, D. Warde-Farley, S. Ozair, A. Courville, Y. Bengio, [Generative Adversarial Nets](#), NIPS, 2014.
 - A. Radford, L. Metz, S. Chintala, [Unsupervised Representation Learning with Deep Convolutional Generative Adversarial Networks](#), arXiv 1511.06434, 2015.
- GAN Extensions
 - J. Zhao, M. Mathieu, Y. LeCun, [Energy-based Generative Adversarial Networks](#), arXiv 1506.03365, 2015.
 - M. Arjovsky, S. Chintala, L. Bottou, [Wasserstein GAN](#), arXiv 1701.07875, 2017.
- Evaluations
 - M. Lucic, K. Kurach, M. Michalski, S. Gelly, O. Bousquet, [Are GANs Created Equal? A Large-Scale Study](#), arXiv 1711.10337, 2017.